

[0086] The commonest class of error-correcting codes are linear error-correcting codes. Almost all of the error-correcting codes presently used in practice are linear. It is convenient, although not necessary, to choose the decoding function of a linear error-correcting code for use in embodiments of the present invention. One property of linear error-correcting codes that is useful in a number of applications is that it is easy to select a codeword c uniformly at random from the set of codewords C .

[0087] It should be noted, however, that an error-correcting code traditionally involves changing a message m to a codeword c before transmission 30. In some situations, however, the translation function g cannot be applied effectively. For instance, when the message m itself contains errors, generating redundancy is problematic. The errors in the message m may well be propagated and reinforced by the redundancy in the corresponding codeword c . This situation exists in the case of a secret pattern that comprises a sequence of discrete graphical choices. It may be difficult for a user to make or repeat discrete graphical choices on a graphical interface without errors; accordingly, a sequence of values that corresponds to a secret pattern should be considered a message m that includes errors. Thus, embodiments of the present invention do not use error-correcting codes in the traditional way.

[0088] Embodiments of the present invention use the decoding function f of an error-correcting code to relate a value, which corresponds to a discrete graphical choice, to a codeword c . In some embodiments, the value is treated as a corrupted codeword i in an error-correcting code. In such embodiments, the decoding function f decodes the value into a codeword c as if the value were a corrupted codeword i .

[0089] Embodiments of the invention do not make use of the translation function g or the reverse translation function g^{-1} of the error-correcting code. In consequence, such embodiments do not map a message m from the message space 10 to a codeword c from the set of codewords C in codeword space 20. Nor do such embodiments map a codeword c from the set of codewords C in codeword space 20 back to a message m from the message space 10. In fact, such embodiments do not use the message space 10 at all.

[0090] The enrollment process illustrated in FIG. 2 includes selecting a codeword c for a value (STEP 230). The value is an n -bit string that corresponds to a discrete graphical choice. The graphical choice may be any sort of discrete input to a graphical interface, such as the selection of a region, an area, or a point on the graphical interface. The codeword c that is selected for a value is also an n -bit string. In some embodiments, STEP 230 involves applying a decoding function f of an error-correcting code to a value. In one such embodiment, the decoding function f is part of a linear error-correcting code.

[0091] In one embodiment, the error-correcting code has a dimension d in which codewords are of the form $\langle Ra_1, Ra_2, \dots, Ra_d \rangle$ such that a_i is an integer and R is a real-valued code parameter and the decoding function f as applied to vector $\langle x_1, x_2, \dots, x_d \rangle$ simply rounds each element x_i to the integer $a_i R$ that is closest. In a related embodiment, where there are ambiguities, a deterministic or randomized tie-breaking algorithm is used, or both possibilities are checked.

[0092] FIG. 9 illustrates a geometric analogy for selecting a codeword c for a value x (STEP 230), according to one

embodiment of the present invention. The set of codewords C are represented as the set of points c_1, c_2, c_3 , and c_4 on the u - v plane; mathematically expressed as $C = \{c_1, c_2, c_3, c_4\}$. The value x is represented as a point on the u - v plane in FIG. 9 with the coordinates (30, 595). The decoding function f associated with this example, but not shown, selects the codeword c within the set of codewords C that is nearest to the input. In comparison, the decoding function f in its normal use as part of an error-correcting code would select the codeword c that is nearest to the corrupted codeword i . Accordingly, since in this example the input to the decoding function is the value x , the decoding function f selects codeword c_3 , the codeword nearest to the value x . This process is expressed mathematically as $f(x) = c_3$.

[0093] Note that FIG. 9 illustrates a geometric analogy of an embodiment in which the decoding function f has no minimum distance in contravention to the usual case. A decoding function f that uses unconstrained codewords selects the codeword c nearest the value x without limit on its distance between the value x and the nearest codeword c . Such a decoding function f will not always be successful in selecting a codeword c for a value x because, for example, a value x may be equidistant to more than one codeword.

[0094] FIG. 10 illustrates a geometric analogy of an embodiment in which the decoding function f selects the codeword c nearest to the value x provided that the distance between the value x and the nearest codeword c falls within the minimum distance of the error-correcting code. In such an embodiment, a decoding function f that uses constrained codewords is used in STEP 230. The dotted line circles surrounding each of the codewords $C = \{c_1, c_2, c_3, c_4\}$ represent the boundaries of the neighborhood of values for which the decoding function f will select the included codeword c . The decoding function f will not select the included codeword c for any value outside the dotted line circle that surrounds the codeword c , even if the value outside the dotted line circle is closer to the enclosed codeword c than to any other codeword. For example, the value x in FIG. 10 does not fall within the boundaries of an area that will map to any codeword c . Accordingly, the decoding function f may output ϕ .

[0095] In either of the foregoing embodiments, the amount of information about the value x that is contained in the corresponding codeword c depends on the number of codewords, or the size of the set of codewords C . The larger the set of codewords, the more information that a codeword contains about its associated value x .

[0096] A comparison of FIG. 11A and FIG. 11B illustrates this concept through another geometric analogy. FIG. 11A shows a value x and a set of one codeword $C = \{c\}$, both as points on a plane. A decoding function f will select the codeword c nearest to the value x in FIG. 11A. Since there is a single codeword c in the set of codewords C in FIG. 11A, the decoding function f will select the codeword c for the value x . Accordingly, knowing that the decoding function selected codeword c for the value x in FIG. 11A provides no information about the true location of the value x on the plane. In comparison, FIG. 11B shows a value x and a set of four codewords, all as points on a plane. A decoding function f will select the nearest codeword c_1 for the value x in FIG. 11B. Since there are four codewords in the set of codewords $C = \{c_1, c_2, c_3, c_4\}$ in FIG. 11B and the value x is